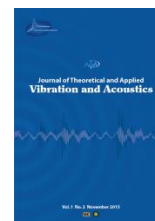




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Damage detection of multi-girder bridge superstructure based on the modal strain approaches

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ABSTRACT

The research described in this paper focuses on the application of modal strain techniques on a multi-girder bridge superstructure with the objectives of identifying the presence of damage and detecting false damage diagnosis for such structures. The case study is a one-third scale model of a slab-on-girder composite bridge superstructure, comprised of a steel-free concrete deck with FRP rebars supported by four steel girders, similar to North Perimeter Red River Bridge in Winnipeg, Manitoba. The modal test data of the slab-on-girder specimen are analyzed by two mathematical methods and Mindlin approach. The Mindlin approach uses a small number of sensors and only the fundamental mode of vibration to obtain the modal strains. The unit-area normalization method produces a more precise damage pattern based on the Mindlin approach than the widely used unit-norm method and is thus a superior method for locating damage in multi-girder bridge structures. A new method is proposed to distinguish the false damage diagnosis that is common in multi-girder systems. Based on the invariant stress resultant theory and direct stiffness assumptions, a level III damage detection process is applied successfully to indicate damage localization and severity estimation of the damaged girder.

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1. Introduction

Damage identification of superstructures is a very important issue for engineering research. This identification is based on utilizing the structural vibration characteristics for damage localization

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and severity estimation. However, the damage at the early stage may not change the vibration characteristics significantly. For eliminating the sensitivity problems of modal parameters to the damage, several alternative methods have been proposed. Rytter[1] classified systematically the existing damage detection methodologies in four general categories: (1) level I: detection of damage; (2) level II: localization of damage; (3) level III: assessment of the severity of damage; and (4) level IV: performance evaluation. Damage detection methods can be further classified as model based and non-model based [2]. In model based methods, the structure should be modeled by finite element analysis.

Among the non-model based methods, it is well recognized the methods that utilize the mode shapes are more efficient in damage identification[3-5]. For this purpose, the methods such as strain mode shapes have been proposed [6, 7]. Pandey *et al.*[8], showed that damage occurred in the structure, led to local changes in the shape of mode shape curvature. Salawu and Williams [9] evaluated the performance of some procedures for locating damage using mode shape curvatures. Mode shape curvatures that introduced as modal strains are widely used in damage identification methods[4]. Wahab and DeRoeck[10], investigated the curvature damage factor in a prestressed concrete bridge. The strain based approaches require the direct measurement of dynamic strains or computing the second derivatives of measured modal displacements. In these methods, the noise induced in the measurement causes errors in the numerical computation of the curvatures. In addition, some numerical methods for obtaining modal curvatures lead to inaccurate results. Maeck and De Roeck[11] and Maeck [2], proposed an optimization method for calculating the curvatures and removing the noise from experimental data. Due to its similarity to Mindlin element theory, the Maeck method was recognized as Mindlin approach [2]. By using Mindlin approach, the modal strains are obtained with good accuracy and the boundary conditions can be imposed. Most strain based methods fall in level I and level II categories. However, some new studies have developed level III & IV methods [12]. The invariant stress resultants (ISR) method is one of the newly developed level III non-model based damage identification methods. The ISR method was first established by Dincal and Stubbs [12] as a strain based approach to identify damages in Euler- Bernoulli beam structures. Dincal and Stubbs [13] demonstrated the ability of ISR method for level III damage identification of I40 bridge. Dincal and Stubbs[14] developed ISR method for damage evaluation of Timoshenko beams. The ISR equations can be applied for both static and dynamic systems [15]. Zhang *et al.* [16] constitute the ISR equations in the case of dynamic loading, utilizing the vibration theory. The authors of the present paper use the principles of the ISR method and direct stiffness assumptions, to study level III damage identification of a specific type of structures, i.e. multi-girder composite bridge superstructure.

In recent years, some research programs have focused on damage identification of composite structural systems that are widely used in bridge construction and long- span floors [17]. Morassi and Rocchetto[18] and Dilella and Morassi[19] conducted experimental and numerical studies on damaged composite beams and showed that the sensitivity of flexural modes are more than other modes for identifying damage. According to Dilella and Morassi[20], an Euler–Bernoulli model of composite beam can precisely characterize the vibration response of damaged composite beams. For stud damage identification in composite decks, Liu and De Roeck[21] developed a damage detection method utilizing the local modal curvature and the wavelet transform. Shih *et al.* [22] developed a multi-criteria procedure based on the changes of natural frequencies, modal flexibility and the modal strain energy for damage detection in slab–girder structures. To

evaluate the condition of shear connectors, Xia *et al.* [23] proposed an efficient damage index. This index that was obtained by the differences between frequency-response functions on the slab and the correlated points on the girder, was able to detect all the damages successfully without any data from the intact structure [23].

Although many efforts have been directed toward the health monitoring of steel–concrete composite systems, various aspects of the subject are still not fully understood. However the relatively large scatter observed in the research studies indicates that some ambiguity such as normalization schemes and spurious modal strains have an important influence on the results of damage diagnosis. The objectives of this study include a) examine and assess the effects of unit-norm and unit-area normalization schemes on accuracy of Mindlin modal strains on steel girders of a composite system, b) synthesis of modal strain energy methods for true damage diagnosis of steel girders, and c) suggesting an approach based on the modal strains for level III damage identification of steel–concrete composite systems.

To accomplish these objectives, this paper investigates the efficiency of Mindlin approach for damage detection of bridge girders by two different normalization methods, namely unit-norm and unit-area normalization methods. The vibration characteristics of a one-third scale model of a composite bridge superstructure are studied. The bridge model comprised of a steel-free concrete deck with FRP rebars supported by four steel girders, similar to North Perimeter Red River Bridge in Winnipeg, Manitoba[24].The influence of the normalization methods on the damage patterns of the model predicted by Mindlin approach is studied and discussed. Some spurious modal strain variations are observed in undamaged girders that introduce the possibility of a false diagnosis of damage at bridge superstructure. By using relative changes of the total modal strain energy, the spurious modal strain changes are identified and the damaged girder is recognized. Finally, the structural damage is localized and quantified by using the ISR relations accompanying direct stiffness assumptions. The results of this study indicate that the proposed process provides a realistic estimate of damage location and severity.

2. Theoretical background

The results of experimental studies and numerical simulation of damaged composite beams demonstrate that flexural modes are more sensitive than other modes for damage identification [18, 19]. Therefore, Euler–Bernoulli model of composite beams can characterize the measured vibration response of composite beams precisely with either high or middle levels of damage [19]. In this Section, by utilizing the fundamental flexural vibration mode of girders and Euler–Bernoulli model, the mathematical basis of this research are presented and discussed.

2.1. Mode Shape Normalization

In modal analysis the scaling procedure that applied for mode shape normalization has a significant influence on predicting structural damage patterns[24, 25] . To study the effects of the scaling methods for damage identification, the unit-area normalization method is selected and compared with the unit-norm method. The unit-norm normalization is a common method which is derived from mass-normalized modal displacements as the following:

$$\phi_i = \frac{\phi_{0i}}{[\sum_{i=1}^n \phi_{0i}^2]^{1/2}} \quad (1)$$

where ϕ_0 is the i th element of the normalized mode shape vector ϕ with n elements; and ϕ_{0i} is the i th element of the primary mode shape vector ϕ_0 . This scheme assumes the uniform mass distribution for the structure. This assumption, is suitable for prismatic beam-like structures [24].

Another global-based normalization method, the newly developed unit-area method, provides a unique definition of mode shape [24]. This method is also well-suited for use in damage identification methods in the early stages. It is similar to the normalization method developed by Huth *et al.*[25]. The unit-area normalized mode shapes are obtained by Eq. (2):

$$\phi_i = \frac{\phi_{0i}}{Area(\phi_0)} \quad (2)$$

where ϕ_i is the i th element of the normalized mode shape vector ϕ with n elements; and ϕ_{0i} represents the i th element of the primary mode shape vector ϕ_0 . The area surrounded by the graph of the magnitude of the mode shape is indicated by $Area(\phi_0)$ in Eq. (3).

$$Area(\phi_0) = \int_0^1 |\phi_0(x)| dx \quad (3)$$

The mode shape function $\phi_0(x)$ is obtained by fitting a natural cubic spline interpolation function to the modal displacements at measurement points in distance x along each girder line. This interpolation creates a piece-wise cubic polynomial with continuous first and second derivatives at sensor locations and zero curvature at the supports[24]. The measurement line should be first scaled equal to one. Thus, the range of integration in Eq. (3) is represented from 0 to 1.

2.2. Mindlin Modal Strains

Modal curvatures or modal strains are effective for damage detection and localization and this has made the method one of the most practical tools being widely used. The most appealing features of modal strains methods consist of high damage sensitivity and immediate damage localization[4]. By using the central difference method, the modal curvatures can be obtained [26]. When the quality of measurements is low, the false damage indications are observed [27]. Furthermore, the environmental or boundary conditions are very influential in the accuracy of modal curvature calculations. By applying some smoothing techniques such as b-spline and global smoothing (polynomial), the modal strains become better and more accurate. However, these techniques are not able to impose boundary conditions. To overcome these problems, Maeck [2] developed the smoothing technique based on constrained optimization and penalty factors. This method named mixed approach, can remove the measurement errors and impose the boundary conditions.

The procedure of the mixed approach for obtaining optimum modal displacements and curvatures is similar to the finite element method that defines the number of nodes and elements for the structure. For each element, the linear shape functions N_i are used. The elements have two

end nodes with three degrees of freedom including: the modal vertical displacement, v , the modal rotation, ψ , and the modal curvature, κ . The nodal degrees of freedom are approximately independent. It resembles the Mindlin plate elements that rotations are independent of the deflections. Due to this resemblance, this method is called the Mindlin approach [2]. In Mindlin's approach, the modal curvatures and torsion rates are obtained by the objective function π presented in Eq. (4) [2, 28].

$$\pi = \int \frac{(v - \phi_m^b)^2}{2} dx + \frac{\hat{\alpha} L_e^2}{2} \int \left(\psi - \left(\frac{dv}{dx} \right) \right)^2 dx + \frac{\hat{\beta} L_e^4}{2} \int \left(\kappa - \left(\frac{d\psi}{dx} \right) \right)^2 dx \quad (4)$$

In Eq. (4), ϕ_m^b and L_e denote the measured mode shape and the element length respectively. Two dimensionless penalty factors $\hat{\alpha}$ and $\hat{\beta}$ are added to enforce the constraint conditions. The desired displacements, rotations, and curvatures are achieved by solving the equation system that is obtained by deriving the objective function π with respect to the unknown degrees of freedom. The values of the penalty factors are chosen to avoid the locking of the equation system [2, 29].

By utilizing Mindlin modal strains and basic relationship for beam-like structures (Eq.(5)), Maeck[2] elaborated direct stiffness calculation technique (DSC) to assess the localized damage.

$$\kappa(x) = \frac{M(x)}{EI} \quad (5)$$

According to Eq. (5), the modal curvature ($\kappa(x)$) in each section is equal to the modal inertia bending moment $M(x)$ in that section divided by the corresponding bending stiffness (EI). In the DSC method, for each bending vibration mode, the modal inertia forces and modal curvatures are calculated to estimate the bending stiffness along the beam.

2.3. Modal Strain Energy

Modal strain energy has received so much attention during the last two decades. Stubbs *et al.*[30] were the pioneer researchers who applied the concept of strain energy to detect the structural damage of steel bridges. Later, Stubbs *et al.* [31] and Topole and Stubbs [32] investigated the feasibility of this method by considering a few modal parameters. This method was appropriate for beam-like structures. Later, Shi *et al.*[33] proposed a new algorithm based on the change of modal strain energy in each structural element due to the damage. Shi *et al.*[34] modified their proposed algorithm to reduce the truncation error in computation, avoid the finite element errors and improve its convergence rate. Because of the model-based characteristics of Shi *et al.* algorithm[34], it is ~~time~~ time- consuming and not suitable for every practical case.

In this paper, the non-model-based modal strain energy concepts are applied to steel bridge girders and flexural vibration modes of the girders are considered. The Bernoulli–Euler modal strain energy equation is used. Considering a three-dimensional beam of length L , the strain energy is represented by [35]:

$$U = \frac{1}{2} \int_0^L \left[EI_z(x) \left(\frac{\partial^2 v}{\partial x^2} \right)^2 + EI_y(x) \left(\frac{\partial^2 w}{\partial x^2} \right)^2 + EA(x) \left(\frac{\partial u}{\partial x} \right)^2 + GJ_x(x) \left(\frac{\partial \psi}{\partial x} \right)^2 \right] dx \quad (6)$$

where u , w and v are, respectively, the displacements in the x , y and z directions. In Eq. (6) ψ is a rotational displacement about x -axis. EI_z and EI_y represent, respectively, the flexural rigidities about z and y axes. EA and GJ_x are the longitudinal and the torsional rigidities. In this study that the flexural rigidity about z -axis is considered, the only first term of Eq. (6) is used and EI_z is replaced by EI as the following:

$$U = \frac{1}{2} \int_0^L \left[EI_z(x) \left(\frac{\partial^2 y}{\partial x^2} \right)^2 \right] dx \quad (7)$$

The modal strain energies associated with mode shape ϕ_i , before and after damage are given by Eqs. (8) and (9):

$$U_i = \frac{1}{2} \int_0^L \left[EI(x) \left(\frac{\partial^2 \phi_i}{\partial x^2} \right)^2 \right] dx \quad (8)$$

$$U_i^* = \frac{1}{2} \int_0^L \left[EI^*(x) \left(\frac{\partial^2 \phi_i^*}{\partial x^2} \right)^2 \right] dx \quad (9)$$

In these equations, asterisks identify the stiffness, the strain energy and the i th eigenvector of the damaged structure. Using the generalized mean value theorem, when f is continuous and g non-negative and integrable, one can write:

$$\exists \hat{x} \in [a, b] \int_a^b f(u)g(u)du = f(\hat{x}) \int_a^b g(u)du \quad (10)$$

Assuming that EI is essentially constant over the length of the beam for both undamaged and damaged modes and using Eq. (10), then Eqs. (8) and (9) can be rearranged to:

$$U_i = \frac{1}{2} \widehat{EI} \int_0^L \left[\left(\frac{\partial^2 \phi_i}{\partial x^2} \right)^2 \right] dx \quad (11)$$

$$U_i^* = \frac{1}{2} \widehat{EI}^* \int_0^L \left[\left(\frac{\partial^2 \phi_i^*}{\partial x^2} \right)^2 \right] dx \quad (12)$$

Considering ($\widehat{EI}^* \cong \widehat{EI}$), the relative modal strain energy change before and after damage states can be obtained by Eq. (13):

$$\Delta U_i = \frac{U_i^* - U_i}{U_i} = \frac{\int_0^L \left[\left(\frac{\partial^2 \phi_i^*}{\partial x^2} \right)^2 \right] dx - \int_0^L \left[\left(\frac{\partial^2 \phi_i}{\partial x^2} \right)^2 \right] dx}{\int_0^L \left[\left(\frac{\partial^2 \phi_i}{\partial x^2} \right)^2 \right] dx} \quad (13)$$

A reduction in stiffness associated with damage will lead to an increase in curvature. Therefore, due to the extent of damage, the value of ΔU_i in Eq. (13) increases. In multi-girder systems, spurious changes in curvatures are observed but don't lead to an increase in ΔU_i . In these cases, the structure becomes stiffer and the change of relative modal strain energy decreases.

Assuming that the beam is divided into N elements, the strain energy of an element j for a given mode shape i may be expressed by [35]:

$$U_{ij} = \frac{1}{2} \int_{a_j}^{a_{j+1}} \left[EI(x) \left(\frac{\partial^2 \phi_i}{\partial x^2} \right)^2 \right] dx \quad (14)$$

with a_j and a_{j+1} denote the start and end points of the element j. The fractional strain energy F_{ij} , i.e., the ratio of the element strain energy to the beam strain energy can be defined as:

$$F_{ij} = U_{ij}/U_i \quad (15)$$

In the presence of small damages, a first-order approximation can be drawn [35, 36]:

$$F_{ij}^* = F_{ij} + \text{higher-order terms} \quad (16)$$

Substituting Eqs. (10), (11), (12) and (14) into Eq. (15) and employing Eq. (16), lead to [35]:

$$1 = \frac{F_{ij}^*}{F_{ij}} = \frac{U_{ij}^* U_i}{U_{ij} U_i^*} = \frac{\int_{a_j}^{a_{j+1}} EI^*(x) (\partial^2 \phi_i^* / \partial x^2)^2 dx}{\int_{a_j}^{a_{j+1}} EI(x) (\partial^2 \phi_i / \partial x^2)^2 dx} \frac{\int_0^L EI(x) (\partial^2 \phi_i / \partial x^2)^2 dx}{\int_0^L EI^*(x) (\partial^2 \phi_i^* / \partial x^2)^2 dx} \quad (17)$$

$$1 = \frac{\widehat{EI}_j^* \int_{a_j}^{a_{j+1}} (\partial^2 \phi_i^* / \partial x^2)^2 dx}{\widehat{EI}_j \int_{a_j}^{a_{j+1}} (\partial^2 \phi_i / \partial x^2)^2 dx} \frac{\widehat{EI}^* \int_0^L (\partial^2 \phi_i / \partial x^2)^2 dx}{\widehat{EI} \int_0^L (\partial^2 \phi_i^* / \partial x^2)^2 dx} \quad (18)$$

$$\frac{\widehat{EI}_j}{\widehat{EI}_j^*} = \frac{\int_{a_j}^{a_{j+1}} (\partial^2 \phi_i^* / \partial x^2)^2 dx}{\int_{a_j}^{a_{j+1}} (\partial^2 \phi_i / \partial x^2)^2 dx} \frac{\int_0^L (\partial^2 \phi_i / \partial x^2)^2 dx}{\int_0^L (\partial^2 \phi_i^* / \partial x^2)^2 dx} \quad (19)$$

By utilizing the mean value of modal strain energies of n mode shapes, Eq. (19) can be represented as Eq. (20), where β_j is modal strain energy damage index of the beam[35].

$$\beta_j = \frac{\widehat{EI}_j}{\widehat{EI}_j^*} = \frac{1}{n} \sum_{i=1}^n \frac{\int_{a_j}^{a_{j+1}} (\partial^2 \phi_i^* / \partial x^2)^2 dx}{\int_{a_j}^{a_{j+1}} (\partial^2 \phi_i / \partial x^2)^2 dx} \frac{\int_0^L (\partial^2 \phi_i / \partial x^2)^2 dx}{\int_0^L (\partial^2 \phi_i^* / \partial x^2)^2 dx} \quad (20)$$

The β_j damage index can be normalized to obtain the generalized and independent damage index according to Eq. (21)[35]:

$$z_j = (\beta_j - \bar{\beta})/\sigma_\beta \quad (21)$$

where, z_j is the standardized damage index for j th element, $\bar{\beta}$ is the mean of β_j 's and σ_β is the standard deviation of β_j 's. Next, the element is assigned to a damage class via a statistical-pattern-recognition technique or classification algorithm. The damage locations in the structure can be determined by utilizing various classification algorithms such as Bayes' rule, nearest distance or hypothesis testing[36, 37]. Hypothesis tests are advantageous because they present a rigorous and standardized approach for making decisions[38].

A statistical hypothesis test is a method of statistical inference. Commonly, two statistical data sets are compared by hypothesis test [39, 40]. In damage detection problems, the null hypothesis (H_0) and alternative hypothesis (H_1) are defined. H_0 corresponds to element j of the structure that is not damaged and H_1 corresponds to element j of the structure that is damaged. The decisions for damage occurrence are made based on z_η , a threshold level of damage and can be considered as a discriminating level [37]. The symbol η denotes the significance level. By comparing the normalized damage index z_j to z_η , the damaged elements are determined. The decision rules are defined as follows:

$$\text{Choose } H_1 \text{ when } z_j \geq z_\eta; \quad \text{Choose } H_0 \text{ when } z_j < z_\eta$$

in which z_η = a number that reflects the level of significance of the test with the desired confidence level. The decision is made based on the criterion or level of significance for assigning the location of damage[37]. The typical values for the level of significance in damage localization are between 0.05 and .01 with corresponding to z scores.

2.4. Dynamic invariant stress analysis

The invariant stress analysis is a new damage identification method based on the moment-curvature relations. The idea emanated from the invariant stress resultants (ISR) theory. The (ISR) theory, assumes that the resultant internal force distribution in a structural member is not influenced by the occurrence of damage[12]. The structure under consideration must be subjected to the identical loading before and after damage. The ISR theory always satisfies the conditions of statically determinate structures and it is approximately satisfactory for statically indeterminate structures which damaged slightly [12, 13]. The equations of ISR method were developed by assuming that the initial and final systems are subjected to the same dynamic external loading [15, 16]. The dynamic ISR method is a Level III damage evaluation methodology that simultaneously identifies the location, the extent, and the severity of stiffness damage [16].

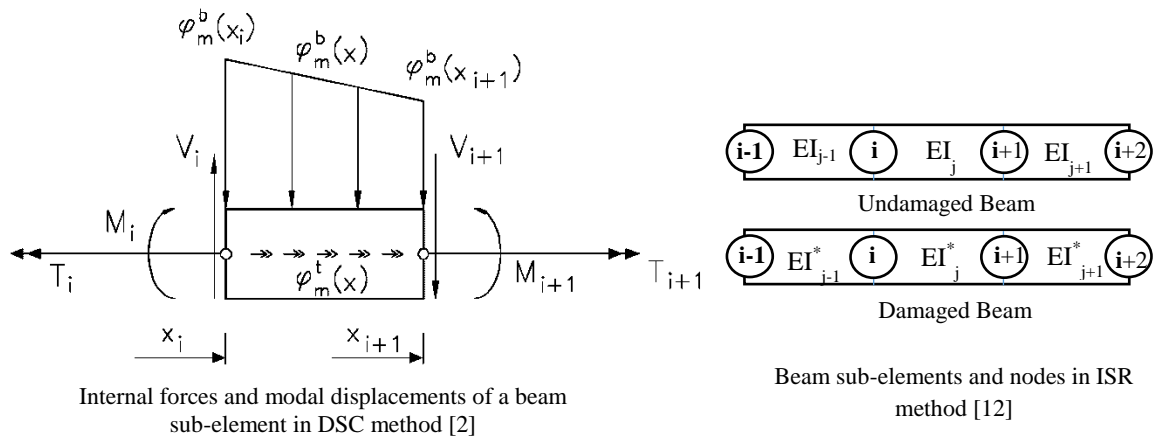


Fig 1. Beam sub-elements and internal forces in DSC and ISR methods

The objectives of this research are to utilize the basic theory of the ISR method by direct stiffness assumptions and apply it to the specific type of structures (multi-girder bridge superstructure). As illustrated in Sec. 2.2 of this paper, Maeck [2] developed DSC technique to calculate the modal curvatures without direct numerical derivation from the modal displacements. The resulting modal curvatures were named Mindlin modal strains. The modal strains combined with modal internal forces, lead directly to an estimation of stiffness decrease in the structure [28, 29]. The DSC method uses the experimental mode shapes for deriving the stiffness. If the mass distribution is assumed to be known, the advantage is that no numerical model is needed to obtain the stiffness distribution for a statically determinant structure[2]. The bending stiffness EI in each section is obtained by calculating the modal internal forces (Eq.(5)). As shown in Fig. (1), for calculation of the internal forces, the inertia forces must be determined.

The inertia forces are derived by using eigenfrequencies and eigenmodes of the beam structure. If the element grid is dense, inertia forces calculated by lumped mass matrix assumption, are enough accurate. In DSC method, for each bending mode, the internal forces of the beam sub-elements due to the inertial load can be calculated[2]. According to Fig. (1), the modal internal forces including shear forces V_i , bending moments M_i and torsional moments T_i are obtained by equilibrium equations. In these calculations, the contribution of rotational inertia turned out to be negligible for the lower modes when a reasonably dense grid is used. In large bridge structures, the lower vibration modes are employed for damage detection and for low levels of damage, the inertia loads of lower modes after small damage remain roughly constant. In this paper, the experimental case study is a large and heavy structure and removing a splice plate does not affect its mass and fundamental frequency considerably. Therefore, the change in internal bending moment M_i of fundamental mode before and after damage can be ignored. This provides the feasibility of the application of the ISR equations in the DSC modal space. Furthermore, the ISR equations can also be utilized when the external loads of the system remain the same before and after damage [15, 16].

Figure (1) shows sub-elements of a beam with NE elements and NN nodes. For arranging the ISR system of equations, the moment curvature relations of the Euler–Bernoulli beam theory should be applied at node i ($x=l_i$) as the followings[12]:

$$M(l_i) = EI_{j-1}\kappa_L(l_i)=EI_j\kappa_R(l_i) \quad (22)$$

According to the Fourier convergence theorem [41], although the curvature is not continuous at $x = l_i$, its value converges to κ_i . The moment curvature relations can be written as Eq. (23).

$$M(l_i) = EI_i\kappa_i(l_i) \quad , \quad \kappa_i = \frac{1}{2}(\kappa_L(l_i) + \kappa_R(l_i)) \quad (23)$$

If the internal forces of the beam don not change due to the damage, Eqs. (24) are satisfied, where the asterisks denote the damaged beam.

$$M^*(l_i) = EI_{j-1}^*\kappa_L(l_i)^*=EI_j^*\kappa_R(l_i)^* \quad , \quad M(l_i) = M^*(l_i) \quad (24)$$

From Eqs. (22), (23) and (24), one can conclude the relationship between beam element stiffness and curvatures [12]:

$$\left(\frac{EI}{EI_j^*} + \frac{EI}{EI_{j-1}^*}\right)\kappa_i = 2\kappa_i^* \quad , \quad \tilde{\beta}_j = \frac{EI}{EI_j^*} \quad (25)$$

Defining the damage ratio $\tilde{\beta}_j$, Eq. (25) can be expressed as[12]:

$$(\tilde{\beta}_j + \tilde{\beta}_{j-1})\kappa_i = 2\kappa_i^* \quad , \quad \tilde{\beta}_j = \frac{EI}{EI_j^*} \quad (26)$$

Equation (26) has a recursive scheme that can be used for obtaining the relation between the damage indices for the j th and $(j + 1)$ th beam elements at the $(i + 1)$ th node. Therefore, for a beam with NN nodes and NE sub-elements, linear equations are written in the form of Eq.(27). Vector $\tilde{\beta}_{(NE \times 1)}$ contains the unknown damage ratios. Matrix $A_{(NN - 2) \times (NE)}$ includes the measured curvatures for the undamaged beam and vector $B_{(NN - 2) \times 1}$ includes the measured curvatures for the damaged beam [12, 13].

$$A_{(NN-2) \times (NE)}\tilde{\beta}_{(NE \times 1)} = B_{(NN-2) \times 1} \quad (27)$$

A system of undetermined linear equations is obtained by this process. Moore–Penrose pseudo-inverse and singular value decomposition (SVD) is utilized to achieve the generalized inverse of the matrix built by rearranging the system of linear equations. The unknown element damage ratios, (i.e., vector $\tilde{\beta}_{(NE \times 1)}$), are acquired by solving these equations. The predicted severity for the j th damaged element is expressed in terms of the damage indicator α_j [12,13]:

$$\alpha_{jP} = \frac{\Delta EI_j}{EI} = \frac{EI_j^* - EI_j}{EI_j} = \frac{1}{\tilde{\beta}_j} - 1 \quad (28)$$

These equations constitute the level III explicit damage identification method. This non-model based damage detection technique together with the DSC assumptions can be used for damage detection of multi-girder superstructures.

3. Experimental case study

In this research, the fundamental vibration data from a one-third scale model of a slab-on-girder composite bridge superstructure are studied and discussed. This structural model was constructed in the Structural Laboratory, University of Saskatchewan, based on a prototype bridge superstructure creating part of the North Perimeter Red River Bridge located in Winnipeg, Manitoba[24]. The composite bridge model comprised of a steel-free concrete deck with FRP rebars supported by four steel girders as shown in Figs.(2), (3) and (4). The bridge deck was fabricated using the design techniques proposed by Mufti *et al.* [42]. The internal arching forces were developed by connecting the top flanges of the girders via steel straps spaced at 800 mm (Fig.(3)). The concrete compressive strength and the steel yielding strength were $f_c=30\text{MPa}$ and $f_y=350\text{ Mpa}$ respectively.



Fig2. One-third scale of composite deck and removal of the splice for damage scenario [24].

This composite bridge system is third-generation of deck slabs that enables the concrete bridge deck to be manufactured without the internal steel reinforcement bars. It is an effort to prevent the corrosion, by eliminating the steel reinforcement bars from the concrete deck slab[43]. The meshes of glass fibre reinforced polymers (GFRP) applied in the concrete slab, can control the cracking due to shrinkage, creep, and temperature variations. In this steel-free composite bridge, the internal arching action extends and the slab does not require any tensile reinforcement [42, 43]. The girders are transversely tied together by steel straps and cross frames to provide the internal arching action. Fig. (3) shows the cross-section view and structural components of this composite system [24]. Several damage states including damage to the steel girders, girder splices, cross bracing diaphragms, steel straps and concrete deck may be occurred. In this study, damage state due to the removing of the bottom splice plate is considered.

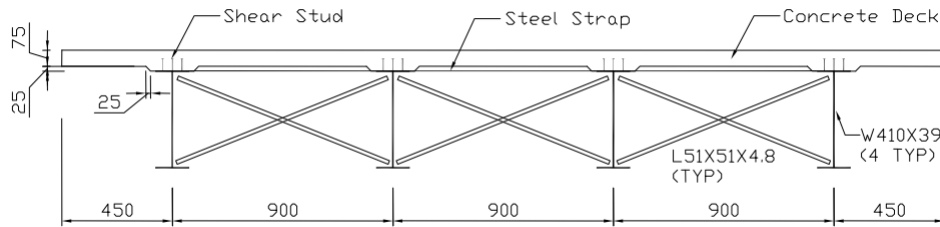


Fig 3. Cross-section of the bridge model deck (dimensions in mm) [24].

The forced vibration tests performed by Wang [24] were conducted in a suitable and controlled laboratory environmental condition. Wang [24] used 28 accelerometer locations to achieve the vibration characteristics of the composite deck (seven accelerometers with the same spacing along each of four girder lines). The harmonic loads for exciting the bridge laboratory model were provided by a hydraulic shaker with different frequencies to reach the calibration measurements efficiently [24].

To introduce the sequential damage scenarios in well-controlled and more facilitate condition, several bolted joints were applied. According to Figs. (2) and (4) a splice plate was applied at the mid-span of Girder 4. The damage location at $x=4.0$ m and $y=2.7$ m, denoted as SP-X4.0Y2.7 in Fig. (4). In this damaging scenario, the bottom splice plate was removed at mid-span of Girder and the flexural rigidity reduced at the location [24].

The experimental data were processed by Wang [24] and the vibration characteristics of the composite deck were obtained using commercial software package SPICE (or MACEC) [44]. In SPICE software, both the Pick Picking method (PP) and the Stochastic Subspace Identification method (SSI) were implemented to obtain the modal properties [44, 45]. The vibration data analysis showed that SSI modal identifications yields more reliable results than the PP method [24].

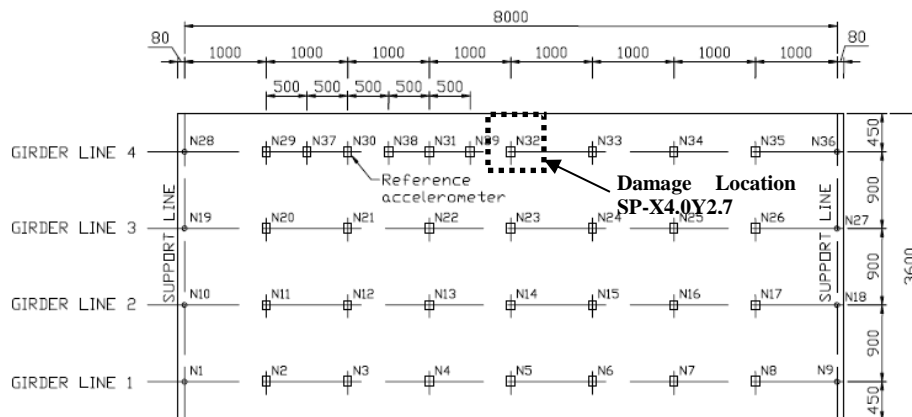


Fig 4. Plan of the composite deck, locations of acceleration measurement points and the location of damage to the steel Girder 4 (dimensions in mm) [24].

The natural frequencies of the system from the harmonic excitation test are presented in Table 1. The natural frequencies decreased as damage was introduced to the structural elements. Damage is associated with a decrease in the eigenfrequencies, an increase in damping values and alteration of the modes of vibration. Changes in eigenfrequencies have shown little promise in detecting the presence of damage.

Table 1. Fundamental frequency of composite bridge superstructure [24]

Fundamental frequency before damage	12.70 Hz
Fundamental frequency after removal the girder splice	12.63 Hz

The experimental dynamic tests and damage scenario of the composite bridge superstructure were simulated by commercial finite element analysis software ANSYS [24]. This simulation, provided the composite action for concrete deck and steel girders. The lateral displacements of the girders were restrained by 2-node linear truss elements as shown in Fig. (3). Wang [24] calibrated the finite element model to the eigenfrequencies and eigenmodes of the undamaged laboratory vibration data. After calibrating the finite element model, the damage state to steel girder splice was introduced into the simulated model. The relative change in the vertical flexural stiffness was obtained by utilizing an individual vertical load at the damage location and calculating the correlated displacement. The results of finite element analysis showed a reduction of 7.76% in the vertical flexural stiffness due to the damage condition shown in Figs. (2) and (4) [24].

4. Analytical study

In this section, the fundamental vibration characteristics of the experimental case study are analyzed. For the large bridge structure under consideration, the sensitivity of higher modes to the damage is less than the first vibration mode [46]. The simply supports of the bridge model consist of the hinge and roller that were applied for two ends of the girders [24]. Several features of the non-model based damage detection process of this composite structure including effects of normalization methods, modal strains calculation, spurious diagnosis, damage localization, and severity estimation are studied and discussed.

4.1. Modal displacements and curvatures

Experimental mode shapes are modal displacements in the modal space. With the aim of damage identification based on the modal displacements, the mode shapes should be normalized consistently to accentuate the local changes due to the damage. It has been observed that the efficiency of the identification process, strongly depends on the special mode shape normalization methods[47]. In the present study, two normalization methods namely unit-norm and unit-area normalization are utilized. By using Eqs. (2) and (3), the unit-area normalized fundamental mode shapes along each girder line are obtained. Fig. (5), shows that the mode shape amplitudes obtained by the two normalization methods are significantly different. The resulting changes in mode shape patterns due to damage are shown in Fig. (6).

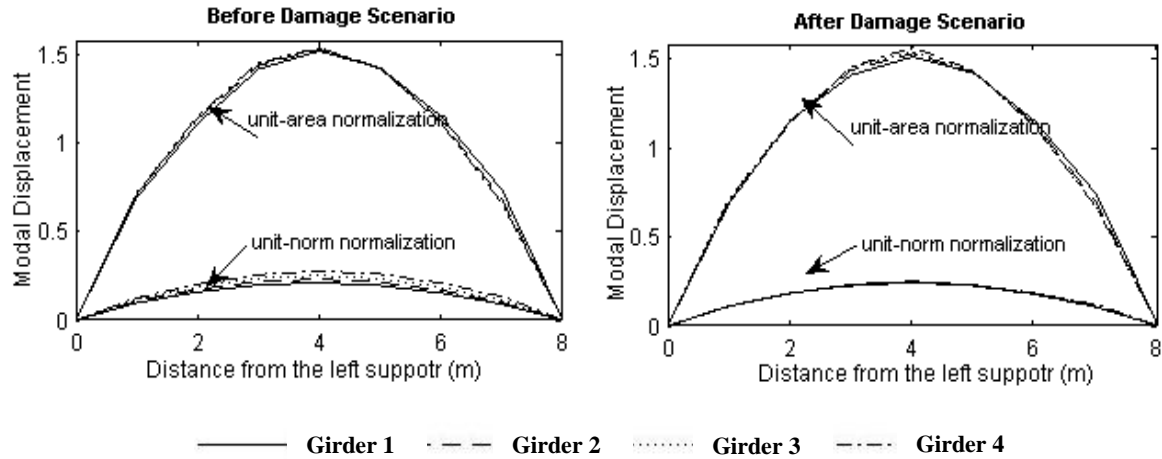


Fig5. Comparison of two normalization methods for the fundamental vibration mode of the bridge Girders.

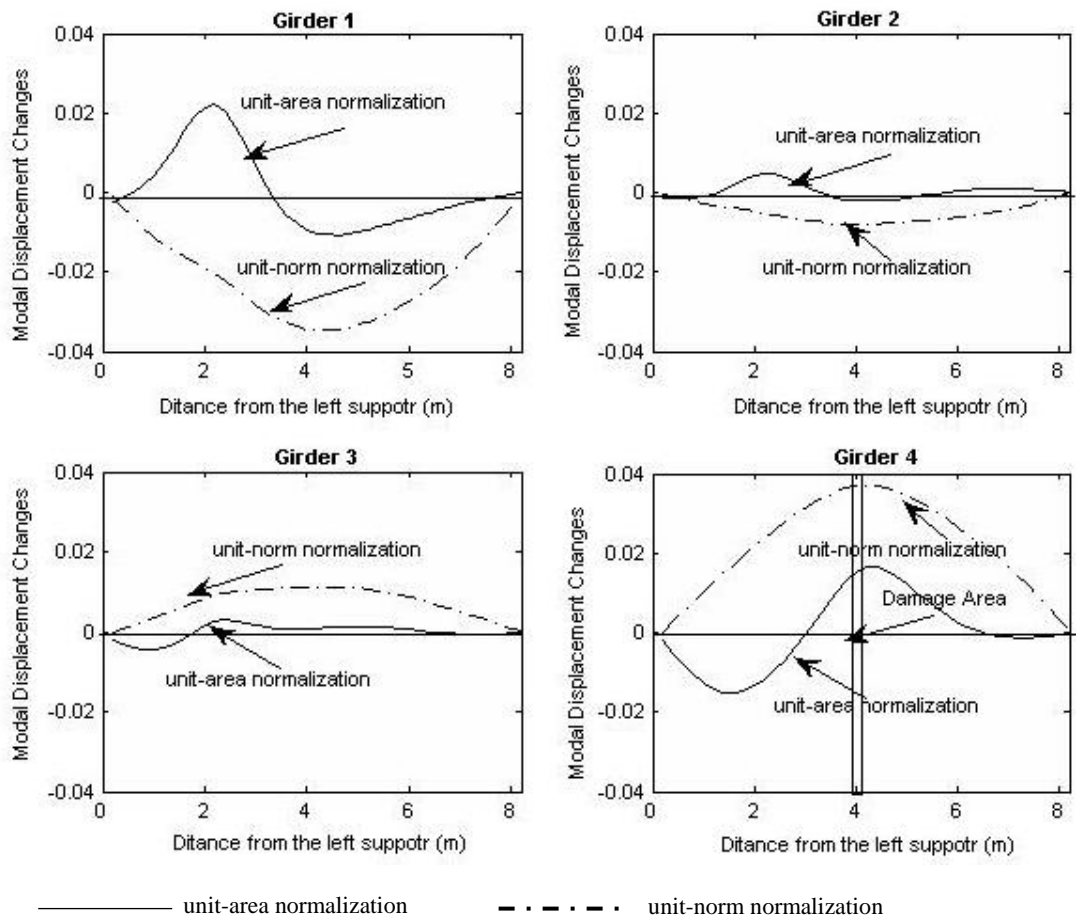


Fig 6. Changes in fundamental modal displacement due to the damage

According to Fig. (6), the unit-area normalization along each girder line can magnify the local changes that became narrow near the feasible damaged regions. On the other hand, plots for unit-norm normalization shows a smooth and nearly symmetric mode shape change along all girder lines. In these smooth plots, the largest positive peak corresponds well to the real location of damage at mid-span of Girder 4. In the unit-area normalization graphs, the convexity at the damaged region in Girder Line 4 is obvious and the damage is localized more precisely. Another large convexity also observed in Girder Line 1, which indicates the possible false damage diagnosis [24]. Furthermore, the changes of modal displacements along Girder lines 2 and 3 are slight, indicating the healthy state of these girders.

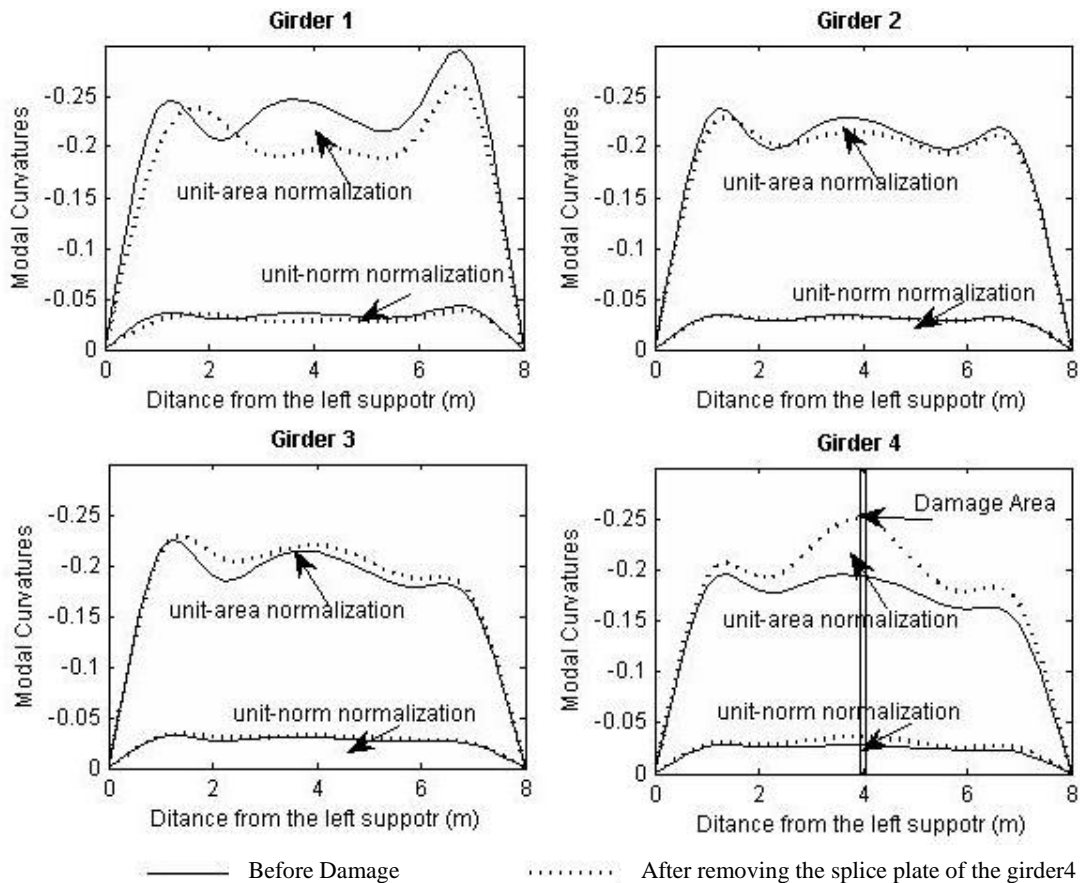


Fig 7. Mindlin modal strain (curvature) of the fundamental vibration modes of the composite bridge girders with different normalization methods

Mode shapes or modal displacement changes are not sensitive enough to the damage location, while the modal strains or modal curvatures changes are more susceptible to the damage location. The calculation of modal strains may be influenced by large mathematical errors. Numerical simulations and experiments proved that the Mindlin technique performs well for modal strain calculation and stiffness determination of beam-like structures[2, 48]. The efficiency of the Mindlin approach for damage detection of concrete beams was investigated by

the authors in the dynamic structural laboratory at Ferdowsi University of Mashhad [48]. A comparison of the results between these studies shows that the effects of normalization methods are more pronounced for multiple girder structures than a simple beam specimen. In this Section, Mindlin approach presented in Section 2.2 is used to calculate the modal strains of the girders.

As shown in Fig. (4), the arrangement of measurement points in the experiment is very coarse and thus the modal strains cannot be obtained with reasonable accuracy. To overcome this problem, by using cubic Spline interpolation functions, the measurement points are increased from 9 to 41 points and the modal strains of each girder are obtained by Mindlin approach. In this study optimum values of two penalty terms $\hat{\alpha}$ and $\hat{\beta}$ (Eq. (4)), are found for the fundamental mode shapes of the girders to minimize the median of relative errors. The optimum values calculated for $\hat{\alpha}$ and $\hat{\beta}$ are 100 and 300 respectively.

Mindlin modal strains were obtained for the previously mentioned normalization methods. The performances of the unit-norm and unit-area normalization methods are shown in Fig. (7). In the damage scenario, the splice plate in the mid-span of the Girder4 was removed and other girders were in the healthy state. A reduction of stiffness associated with damage will lead to an increase in curvature. From Fig. (7), appears that by using the unit-area normalization method a more consistent mode shape is obtained and the modal strain changes are more pronounced than the widely used unit-norm method. All the absolute values corresponding to the unit-area normalization are greater than those of the unit-norm normalization. Although the shape of the unit-norm normalization strain plots are similar to those obtained by unit-area normalization, the resulting modal strain values are very small. Since the largest peak in the damage state in the unit-area normalization graphs, corresponds well to the real location of damage at the middle span of Girder 4, one concludes that the damage can successfully be located. A large convexity is also observed in the middle of Girder4, which makes damage localization relatively explicit. The peak of convexity in Girder4 coincides well with the damage location. However, some large modal strain variations based on the unit-area normalization also exist along Girder Line 1. These variations that have no significant trends to a special location, introduce the possibility of a false diagnosis of damage in Girder 1. This spurious diagnosis which also observed in numerical studies is common for multi-girder systems [24, 49]. As observed in Fig. (7), the amplitudes of modal strains change slightly along Girder lines 2 and 3 after damage. These slight changes may depend on the sensor placement and experimental uncertainties and not due to damage in Girder lines 2 and 3.

These observations reveal the better performance of the unit-area normalization method in damage detection procedures. In the following, the modal strains obtained from unit-area normalized mode shapes are employed to locate damage and distinguish between correct and false diagnoses.

4.2. Spurious damage identification

A common nature of spurious (non-physical) damage identification that arise in multi-girder composite systems is the fluctuations of modal displacements and modal strain diagrams [24, 49]. It is shown that these fluctuations may result in false alarms during the damage detection process. The authors observed that damage detection results of several classic and new methodologies utilizing the modal data of the multi-girder bridge led to the false alarms in Girder

1. Therefore these spurious modal displacements should be discriminated between the modal data.

In the present study, by inspiration of spurious displacement and strains concepts in structural analysis, these non-physical phenomena are identified. Eq. (13) was introduced in Section 2.3 to clarify the false alarms from the exact ones (level I damage identification). It is a strain-based formula obtained by the aim of a generalized mean value theorem and gives the relative modal strain energy changes (ΔU_i). In multi-girder systems, spurious changes in curvatures are observed but don't lead to an increase in ΔU_i . In these cases, the structure becomes stiffer and the change of relative modal strain energy decreases.

For the case study of this article, the ΔU_i values of bridge girders have been calculated by Eq. (13) and Mindlin modal strains obtained from the unit area normalized fundamental mode shape. Table 2 shows that the relative modal strain energy change in Girder 1 is negative. Thus, it is a false diagnosis. The ΔU_i values for Girder 2 and 3 are very small that explains undamaged states. In Girder 4 the ΔU_i value is positive and damage has been occurred.

Table 2. The relative modal strain energy changes (ΔU_i) values of girders of composite bridge superstructure

Girders	Girder 1	Girder 2	Girder3	Girder4
ΔU_i	-0.21932	-0.067241	0.083321	0.31708
Strain energy changes	22% decrease	Small changes	Small changes	32% increase
Damage diagnosis	Spurious	No damage	No damage	Damage occurrence

4.3. Damage localization and severity estimation

In the previous section the damage occurrence in Girder 4 was distinguished from false alarms. However, the location of damage in Girder 4 has not yet been determined. For damage localization of Girder 4, the beam is divided into 40 elements and the strain energy changes of each element are calculated by Eq. (14). The candidate damage elements can be identified by β_j index in Eq. (20). According to statistical approaches, the damaged elements are assumed as random variables β_j for j th element. The damage location is identified by the hypothesis test. Before employing the hypothesis test, the damage indices are standardized using Eq. (21). The decision-making criterion for assigning the location of the damage is based on the Hypothesis testing and damage threshold value. In this study, the threshold value of z_η is selected to achieve the appropriate confidence level. This criterion corresponds to a one-tailed test at a significance level of 0.023 (97.7% confidence level)[50]. The z score (z_η) associated with this significance level equals 2. If $z_j < z_\eta$ null Hypothesis (H_0) is chosen. When $z_j > z_\eta$, the element is damaged and the alternate Hypothesis is chosen.

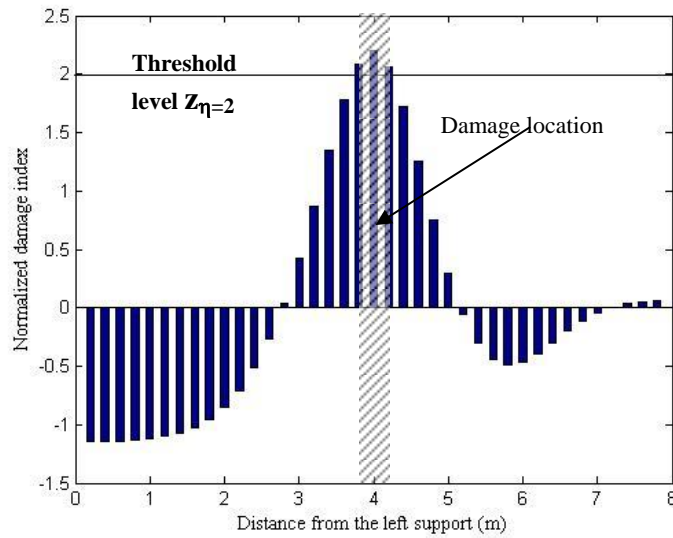


Fig 8. Damage location of Girder 4 by the normalized strain energy index

The results of modal strain energy analysis are shown in Fig. (8) for Girder4. As observed in Fig. (8), the damage location is well determined by normalized damage index. In the mid-span of Girder 4, the normalized damage index values are greater than threshold level ($z_{\eta}=2$). It well coincides with the actual location of the removed splice plate in Girder4. Using the Hypothesis test, a damage index for each degree of freedom of the Girders is obtained. Due to the uncertainties inherent in the practical dynamic tests such as fabrication process and some over design members, the fundamental vibration mode is not entirely symmetric [24]. These asymmetries in the mode shapes affect significantly on the modal strains. As a result, the diagram of modal strain energy index became unsymmetrical.

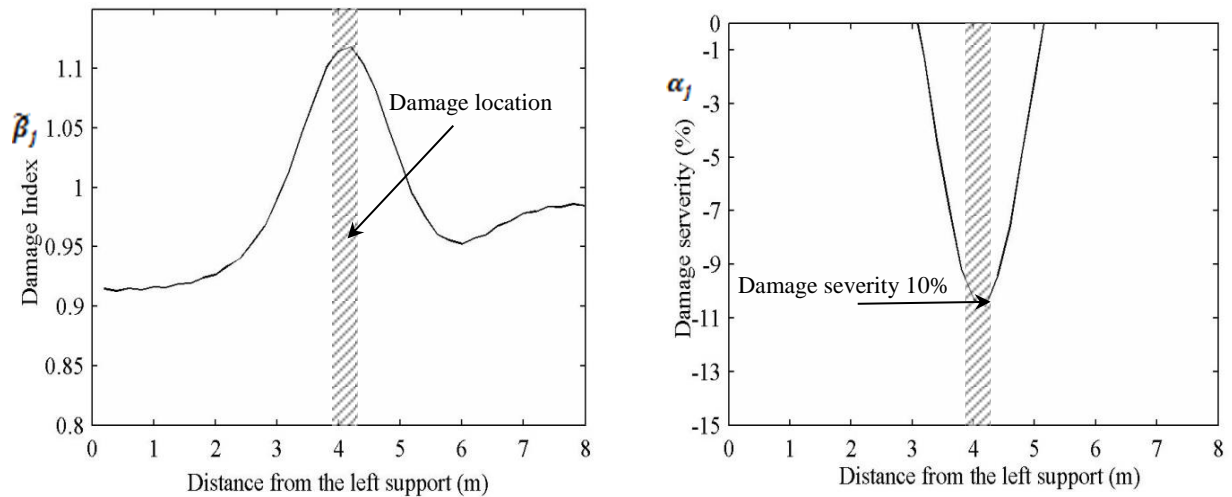


Fig 9. Damage localization and severity estimation of Girder 4 by applying ISR method and DCS

The modal strain energy index provides no information pertaining to damage severity estimates. According to Sec. 2.4, the ISR equations can be applied for the fundamental vibration mode of the beam by DSC modal assumptions. The linear system of ISR equations (Eq. (27)) is arranged by Mindlin modal curvatures, calculated by unit-area normalized modes, and optimal solutions for the system are obtained. Moore–Penrose pseudo-inverse and singular value decomposition methods are also used for solving the undetermined linear system. Solving the equations, yields $\tilde{\beta}_j$ damage indices depicted in Fig. (9). Damage severities (α_j) for damaged elements are calculated by Eq. (28) and utilizing these indices.

As shown in Fig. (9), damaged elements are well localized and the severity estimation is acceptable. The reduction in bending stiffness of the damaged area based on α_j is about 10%. This predicted value is consistent with the finite element calculations for obtaining the relative change in vertical flexural stiffness after damage. As illustrated in Sec. 3 removing the steel girder splice at the mid-span, produced a 7.76% reduction in vertical flexural stiffness at that location [24]. The proposed method predicted a relative reduction of vertical flexural stiffness 2.88% more than finite element calculations. This may be due to the change in modal inertia forces after damage and some experimental and numerical inaccuracies.

The results of this study reveal that the occurrence of damage in a multi-girder bridge superstructure, which in turn affect its dynamic response undesirably, cannot be identified in one stage. In other words, localization and quantification of damage cannot be carried out simultaneously. For these structures, a two-stage method is suggested. In the first stage, the false alarms must be excluded from the modal data by using modal strain energy. In the second stage, the damage should be localized and quantified in the girders. The suggested identification steps are shown in Fig. (10); a guided structural damage detection method based on the modal strains.

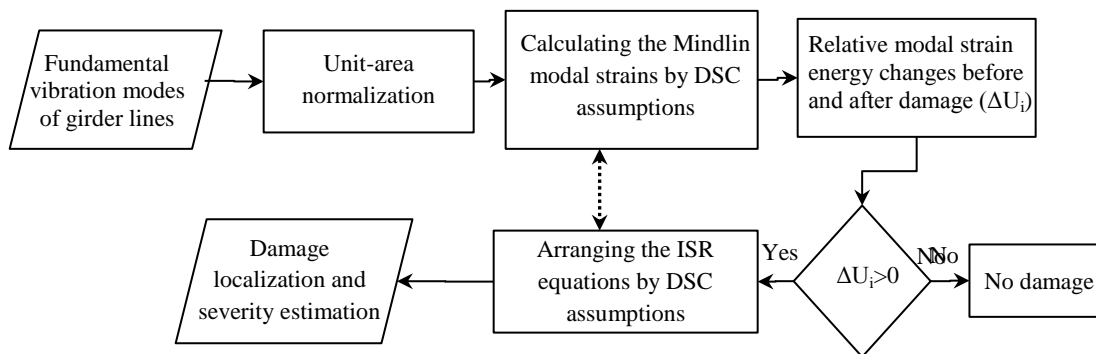


Fig 10. Damage identification process based on the modal strains for multi-girder bridge superstructure

5. Conclusions

In this paper, the fundamental modal characteristics of a one-third scale model of a slab-on-girder composite bridge superstructure were successfully analyzed by modal strain energy method. Using unit-norm and unit-area normalized mode shape data, the modal strains were

calculated by Mindlin's approach. In this process, the effects of two normalization methods on damage detection of the scaled bridge were studied and discussed. Finally, a new damage identification approach was proposed. The following conclusions are drawn:

- Assessments of damage patterns show the drawbacks of a widely used unit-norm normalization method in the damage identification process. The drawbacks consist of smooth and wide spread changes of the mode shapes with no clear trends to the damage location and very small values of modal strains.
- The Mindlin approach is sensitive to the normalization methods. The Mindlin modal strains obtained from the unit-area normalization method produce more pronounced damage patterns. The values of these modal strains are approximately eight times greater than those obtained by the unit-norm method. The accuracy of Mindlin damage pattern based on the unit-area normalization is about 85 percent for a multi-girder bridge structure.
- The spurious diagnosis that is common in multiple girder systems was studied by modal strain approach. The false detection is distinguished from the exact ones by the use of relative total modal strain energy changes in the post and pre-damaged states. The negative values of relative total modal strain energy changes demonstrated the spurious diagnosis.
- The structural damage is localized and quantified by using the ISR equations accompanying direct stiffness assumptions. The results of the level III damage detection process indicate that the process provides an excellent assessment of damage location and severity of the damage. The bending stiffness of the damaged area is estimated to be reduced by 10%, which is 2.88% more than a finite element analysis. This may be due to the change in modal inertia forces after damage and some experimental and numerical uncertainties.

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